

Combinatorics of nonbacktracking and non-cycling walks and their applications to network science

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Setup

The importance of
counting walks

Walk-based centrality

Question 1

Motivation

Problem setting

Four term recurrence

From A to B

Small example

Counting NBT walks

Problem setting

question 2

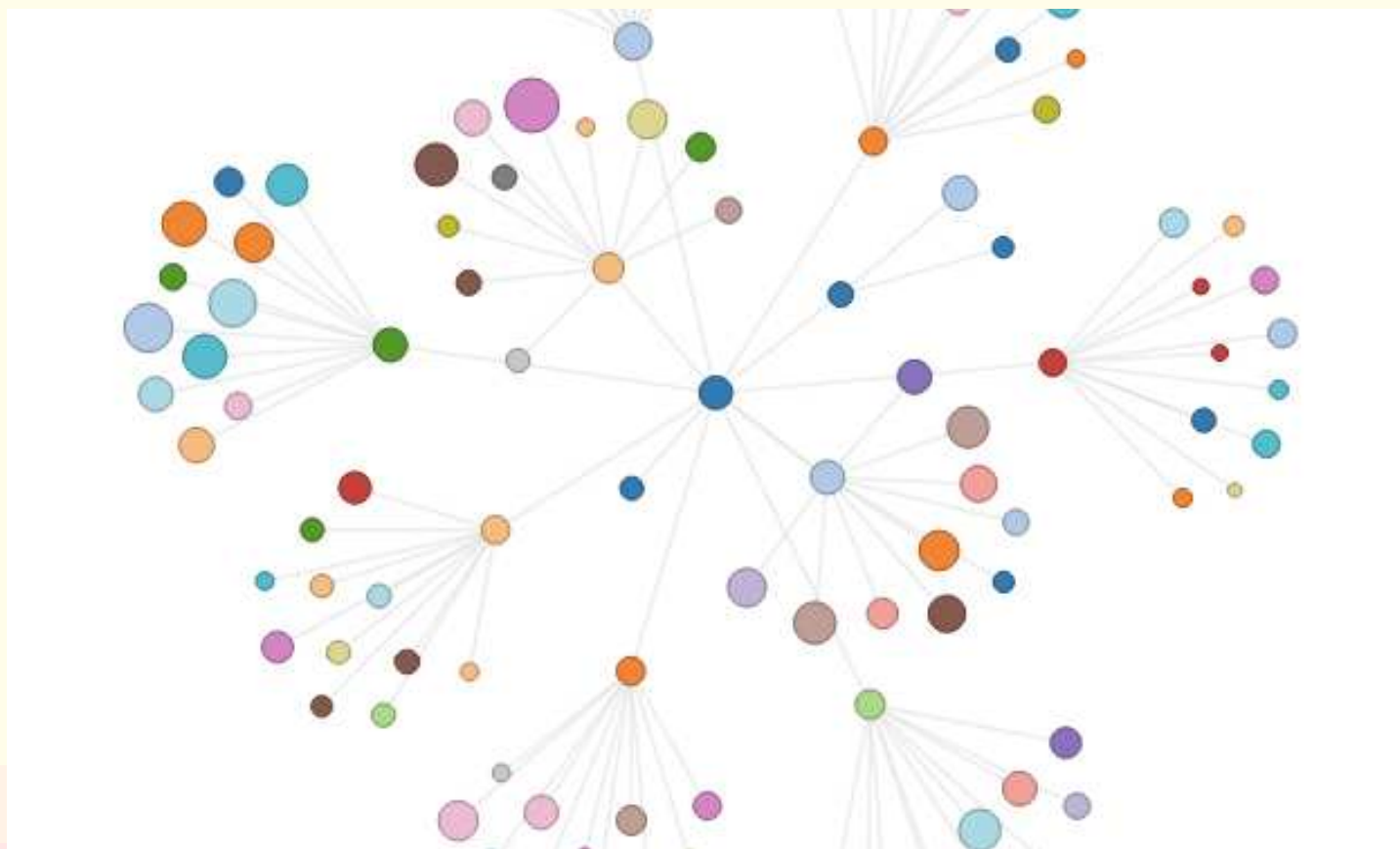
$ABC \dots$ easy as

$123 \dots$

Counting
non- k -cycling walks

What else can we do?

- Graph $G = (V, E)$ with n nodes and m edges, unweighted and w/o loops.
- Every undirected edge $i - j$ is regarded as: $i \rightarrow j$ and $j \rightarrow i$.



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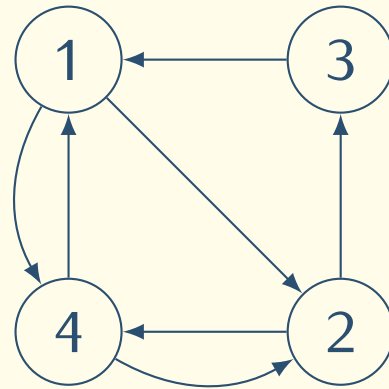
Counting

non- k -cycling walks

What else can we do?

A **walk** is any traversal of the network.

Adjacency matrix: $A = (a_{ij}) \in \mathbb{R}^{n \times n}$, $a_{ij} = 1$ iff $i \rightarrow j$.



$$A = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix}$$

Easy: $(A^2)_{ij} = \sum_{k=1}^n a_{ik} a_{kj}$ counts walks of length two.

Generally: entries of A^r count walks of length r .

Counting walks is at the heart of several clustering and centrality algorithms!

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Let $f(x) = \sum_{r=0}^{\infty} c_r x^r$, then, within the radius of convergence:

$$f(A) = \sum_{r=0}^{\infty} c_r A^r$$

Looking closely at $(f(A))_{ij}$:

$$(f(A))_{ij} = \sum_{r=0}^{\infty} c_r (A^r)_{ij}$$

- it tells us how many walks (up to infinite length) originate at node i and end at node j
- if $c_r \geq 0$ and $c_r \rightarrow 0$ as $r \rightarrow \infty$, longer walks are given less weight.

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What else can we do?

Centrality measures assign scores to nodes in graphs to quantify their importance.

Among the most popular centrality measures:

- *f -subgraph centrality (SC)*

$$\mathbf{x}(t)_i = \mathbf{e}_i^T \left(\sum_{r=0}^{\infty} \mathbf{c}_r t^r A^r \right) \mathbf{e}_i = f(A)_{ii}$$

- *f -total (node) communicability (TC):*

$$\mathbf{y}(t)_i = \sum_{j=1}^n \sum_{r=0}^{\infty} \mathbf{c}_r t^r (A^r)_{ij} = \sum_{j=1}^n (f(A))_{ij} = (f(A)\mathbf{1})_i$$

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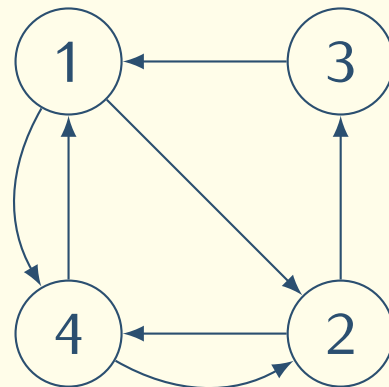
non- k -cycling walks

What else can we do?

Katz centrality: row sums of $I + tA + t^2A^2 + t^3A^3 + \dots$, i.e.:

$$\mathbf{k} = (I - tA)^{-1}\mathbf{1}, \quad \text{for } 0 < t < \rho(A)^{-1}.$$

\Rightarrow Solve a sparse linear system!



Same importance to these
walks of length four:

$1 \rightarrow 4 \rightarrow 2 \rightarrow 3 \rightarrow 1$

$1 \rightarrow 4 \rightarrow 1 \rightarrow 4 \rightarrow 1.$

\dots but the first visits the network more thoroughly.

KATZ, "A new status index derived from sociometric analysis", Psychometrika (1953).

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A **walk (of length $r - 1$)** is any traversal of the network:

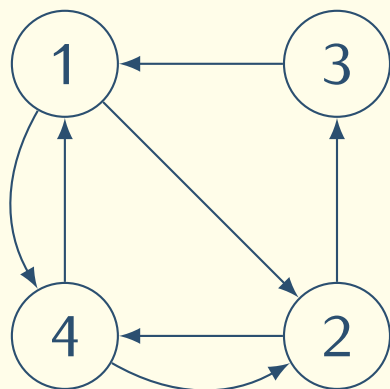
$$\underline{i} = (i_1, i_2, \dots, i_r) \quad \text{or} \quad i_1 \rightarrow i_2 \rightarrow \dots \rightarrow i_r.$$

A walk is said to be **non-backtracking (NBT)** if it does not contain any instance of the form $i \rightarrow j \rightarrow i$.

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$1 \rightarrow 4 \rightarrow 2 \rightarrow 3 \rightarrow 1$ is NBT

$1 \rightarrow 4 \rightarrow 1 \rightarrow 4 \rightarrow 1$ is backtracking.

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Question:

- Can we define NBTW-based subgraph centrality and total communicability indices, using entries or sum of entries of

$$c_0 p_0(A) + c_1 t p_1(A) + c_2 t^2 p_2(A) + c_3 t^3 p_3(A) + \dots$$

where $p_r(A)$ generalizes A^r to the NBT setting, i.e., it counts NBTWs of length r , and $t > 0$ is selected so that the series converges.

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What else can we do?

Non-backtracking walks have been suggested and analyzed in a wide range of fields including (but not limited to!)

- spectral graph theory [Angel, Friedman, Hoory, Horton, Stark, Terras, ...],
- number theory [Terras, ...],
- discrete mathematics [Bowen, Lanford, Stark, Terras, ...],
- stochastic analysis [Alon, Benjamini, Lubetzky, Sodin, ...],
- applied linear algebra [Tarfulea, Perlis, ...],
- computer science [Zaade, Krzakala, Zdeborová],
- ...

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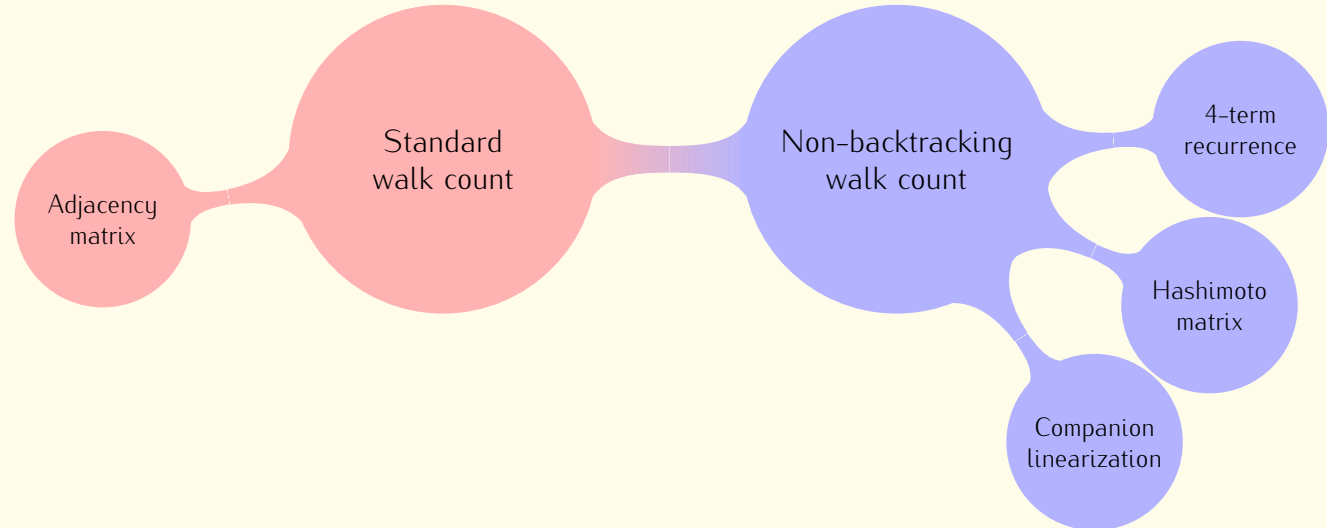
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- ...

In Network Science:

- finding communities [Kawamoto, Krzakala, Moore, Mossel, Zhang,...];
- assigning centrality values to nodes [Martin, Zhang, Newman, Pastor-Satorras, Castellano, Flores, Criado, and many others].

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What else can we do?

- NBTWs visit the network more thoroughly;
- NBTW-based measures avoid localization;
- They can be computed at the same (or lower) computational costs;
- Larger radius of convergence;
- High versatility from the viewpoint of Linear Algebra



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Let $p_r(A) \in \mathbb{R}^{n \times n}$ be such that

$$(p_r(A))_{ij} = |\{\text{NBTW s of length } r \text{ from node } i \text{ to node } j\}|.$$

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Given $f(A) = \sum_{r=0}^{\infty} c_r t^r A^r$, let the non-backtracking counterpart of the matrix function $f(A)$ be:

$$F(A) := \sum_{r=0}^{\infty} c_r t^r p_r(A).$$

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Define the *NBTW-based SC* of node i as:

$$\mathbf{x}_2(i) = (F(A))_{ii}$$

and the *NBTW-based TC* of node i as:

$$\mathbf{y}_2(i) = (F(A)\mathbf{1})_i.$$

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Theorem: Let A be the adj. matrix of an unweighted digraph, $D = \text{diag}(\text{diag}(A^2))$, and $N = A - A \circ A^T$. Then,

$$\begin{aligned} p_0(A) &= I, \\ p_1(A) &= A, \\ p_2(A) &= A^2 - D \end{aligned}$$

and

$$p_r(A) = p_{r-1}(A)A + p_{r-2}(A)(I - D) - p_{r-3}(A)N, \quad \forall r \geq 3.$$

TARFULEA & PERRIS, "An Ihara formula for partially directed graphs", LAA (2009).

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$$p_{r+3}(A) = p_{r+2}(A)A + p_{r+1}(A)(I - D) - p_r(A)N.$$

Entrywise:

$(p_{r+3}(A))_{ij} =$	$\overbrace{i \rightarrow \dots \rightarrow \star \rightarrow \star \rightarrow \star \rightarrow j}^{\text{NBTW of length } r+3}$
$+ (p_{r+2}(A)A)_{ij}$	$i \rightarrow \dots \rightarrow \star \rightarrow \star \rightarrow \ell \rightarrow j$

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$+ (p_{r+1}(A))_{ij}$	$i \rightarrow \dots \rightarrow \ell \rightarrow j \rightarrow \ell \rightarrow j$
$- (p_r(A)N)_{ij}$	it must hold $j \leftrightarrow \ell$

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The non-backtracking analogue of Katz centrality is:

$$\mathbf{k}_{NBT} := F(A)\mathbf{1} = \sum_{r=0}^{\infty} t^r p_r(A)\mathbf{1}.$$

Theorem: Let A , N , and D be defined as before. Moreover, if we use $c_r = 1$ and $t > 0$ is such that $F(A) = \sum_{r=0}^{\infty} t^r p_r(A)$ converges, then

$$[I - At + (D - I)t^2 + Nt^3]F(A) = (1 - t^2)I$$

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$$\mathbf{k}_{NBT} = (1 - t^2)[I - At + (D - I)t^2 + Nt^3]^{-1}\mathbf{1}$$

\implies same cost as Katz.

- $i - j \iff i \rightarrow j \text{ and } j \rightarrow i$
- $G = (V, E)$ with $n = m_1$ nodes and m_2 edges;
- **Adjacency matrix:** $A = W_1 = P_1$;
- Source and target matrices: $L_1, R_1 \in \mathbb{R}^{m_2 \times m_1}$ of P_1 :

$$(L_1)_{i\ell} = \begin{cases} 1 & \text{if } i_1 = \ell \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad (R_1)_{i\ell} = \begin{cases} 1 & \text{if } i_2 = \ell \\ 0 & \text{otherwise} \end{cases}$$

- $W_2 = R_1 L_1^T$;
- Hashimoto matrix:

$$B = P_2 = W_2 - \Delta_2,$$

where $\Delta_2 = W_2 \circ W_2^T$ and \circ entry-wise product.

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We want to concatenate $\underline{i} = (i_1, i_2)$ and $\underline{j} = (j_1, j_2)$ without them backtracking:

$$i_1 \rightarrow i_2 = j_1 \rightarrow j_2 \quad \text{and} \quad i_1 \neq j_2$$

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Entrywise it holds:

$$(W_2)_{\underline{ij}} = (R_1 L_1^T)_{\underline{ij}} = \delta_{i_2 j_1}$$

$$(P_2)_{\underline{ij}} = (W_2 - W_2 \circ W_2^T)_{\underline{ij}} = \delta_{i_2 j_1} (1 - \delta_{i_1 j_2})$$

since

$$(W_2 \circ W_2^T)_{\underline{ij}} = (W_2)_{\underline{ij}} (W_2)_{\underline{ji}} = \delta_{i_2 j_1} \delta_{j_2 i_1}$$

where δ is the Kronecker delta.

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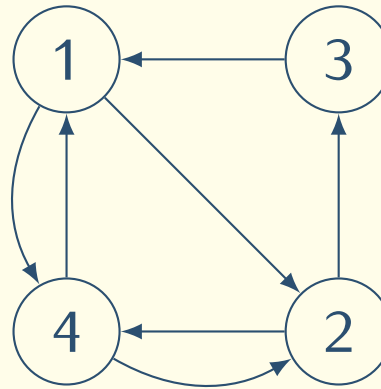
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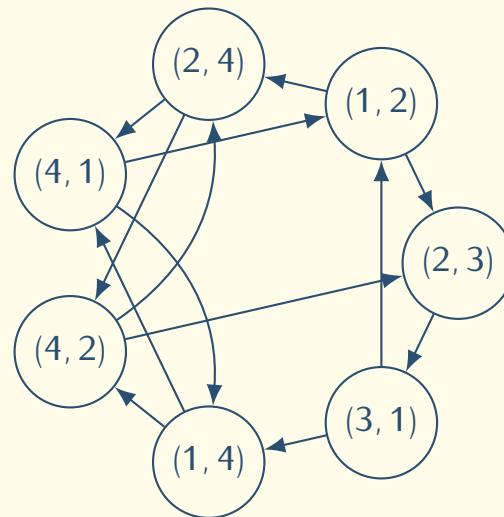
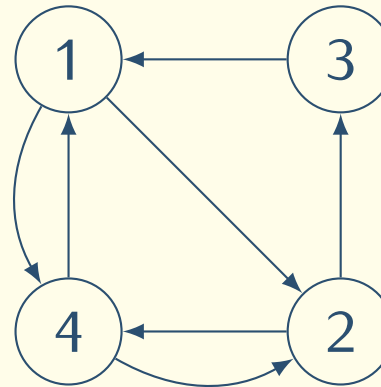
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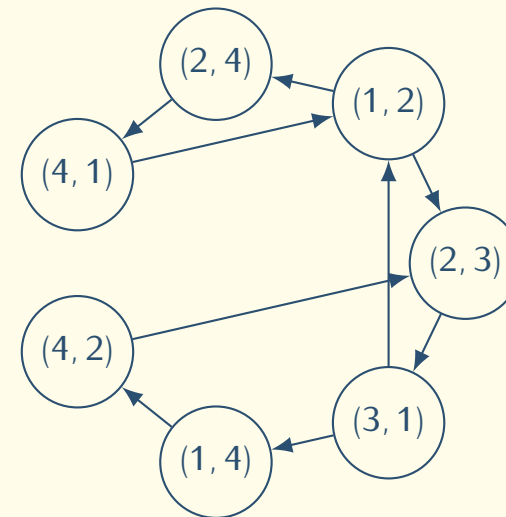
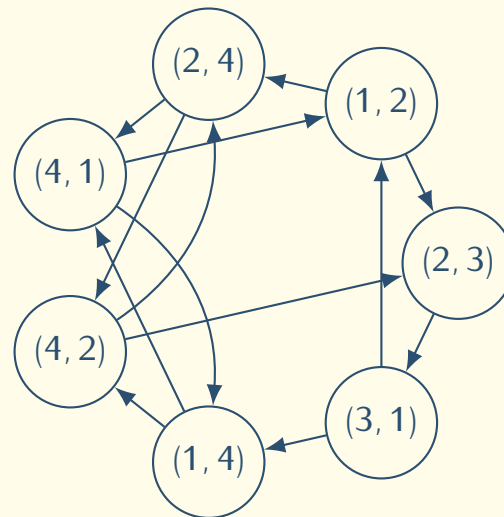
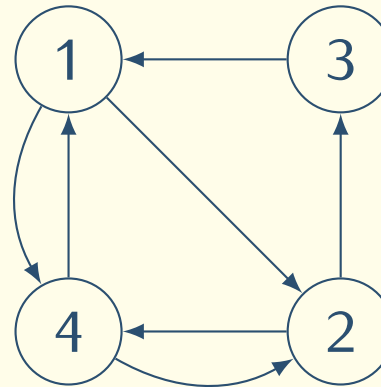
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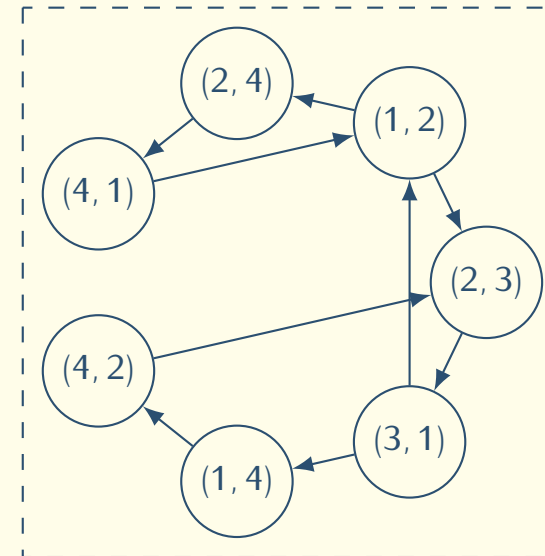
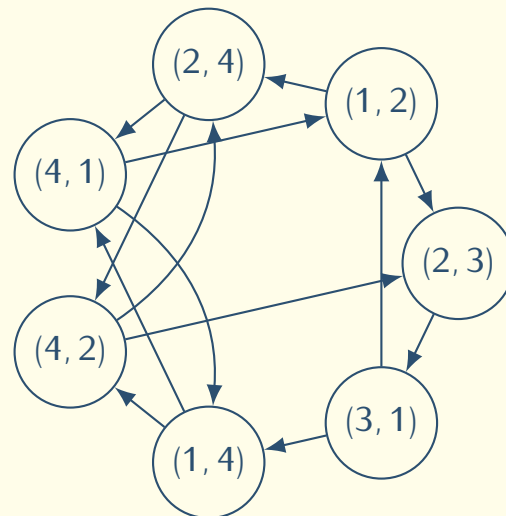
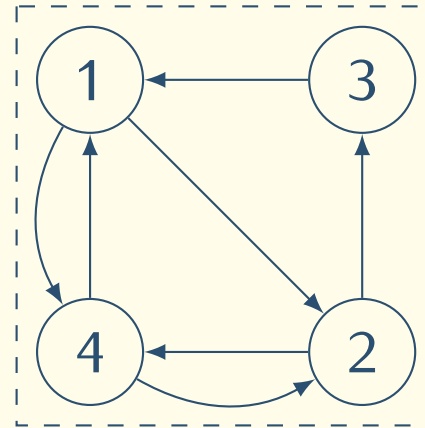
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$$L_1^T(B^r)R_1 = L_1^T(P_2^r)R_1 = p_{r+1;2}(A)$$

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where

$$f(z) = \sum_{r=0}^{\infty} c_r z^r \quad \text{and} \quad \partial f(z) := \sum_{r=0}^{\infty} c_{r+1} z^r$$

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Let $p_{r;k}(A)$ entrywise defined as

$$(p_{r;k}(A))_{ij} = \#\{(i_1 = i, \dots, i_{r+1} = j) \mid \text{w/o cycles of length} \leq k\}$$

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Given $f(A) = \sum_{r=0}^{\infty} c_r t^r A^r$, let the non- k -cycling counterpart of the matrix function $f(A)$ be:

$$F_k(A) := \sum_{r=0}^{\infty} c_r t^r p_{r;k}(A).$$

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Define the *non- k -cycling SC* of node i as:

$$\mathbf{x}_k(i) = (F_k(A))_{ii}$$

and the *non- k -cycling TC* of node i as:

$$\mathbf{y}_k(i) = (F_k(A)\mathbf{1})_i.$$

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Question: Can we define non- k -cycling subgraph centrality and total communicability indices, using entries or sum of entries of

$$c_0 p_{0;k}(A) + c_1 t p_{1;k}(A) + c_2 t^2 p_{2;k}(A) + c_3 t^3 p_{3;k}(A) + \dots$$

where $p_{r;k}(A)$ generalizes A^r to the non- k -cycling setting and $t > 0$ is selected so that the series converges.

$$\mathbf{x}_k(t)_i = \left(\sum_{r=0}^{\infty} c_r t^r p_{r;k}(A) \right)_{ii}$$

and

$$\mathbf{y}_k(t)_i = \left(\sum_{r=0}^{\infty} c_r t^r p_{r;k}(A) \mathbf{1} \right)_i$$

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- For $k = 2, 3, \dots$, given $P_{k-1} \in \mathbb{R}^{m_{k-1} \times m_{k-1}}$
- Source and target matrices $L_{k-1}, R_{k-1} \in \mathbb{R}^{m_k \times m_{k-1}}$ of P_{k-1} :

$$(L_{k-1})_{i\ell} = \begin{cases} 1 & \text{if } i_j = \ell_j \text{ for } j = 1, \dots, k-1 \\ 0 & \text{otherwise} \end{cases}$$

$$(R_{k-1})_{i\ell} = \begin{cases} 1 & \text{if } i_{j+1} = \ell_j \text{ for } j = 1, \dots, k-1 \\ 0 & \text{otherwise} \end{cases}$$

- $W_k = R_{k-1} L_{k-1}^T$ (k th order De Bruijn graphs of paths in the network.)
- **Non- k -cycling matrix**

$$P_k = W_k - \Delta_k,$$

$$\text{where } \Delta_k = W_k \circ (W_k^T)^{k-1}$$

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We want to concatenate $\underline{i} = (i_1, i_2, \dots, i_k)$ and $\underline{j} = (j_1, j_2, \dots, j_k)$ without them closing a k -cycle:

$$i_1 \rightarrow i_2 = j_1 \rightarrow i_3 = j_2 \rightarrow \dots \rightarrow i_k = j_{k-1} \rightarrow j_k$$

and

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$$(P_k)_{\underline{i}\underline{j}} = (W_k - W_k \circ (W_k^T)^{k-1})_{\underline{i}\underline{j}} = \prod_{\ell=1}^{k-1} \delta_{i_{\ell+1}, j_\ell} (1 - \delta_{i_1 j_k})$$

since

$$(W_k^T)_{\underline{i}\underline{j}}^{k-1} = \delta_{i_1 j_k}$$

where δ is the Kronecker delta.

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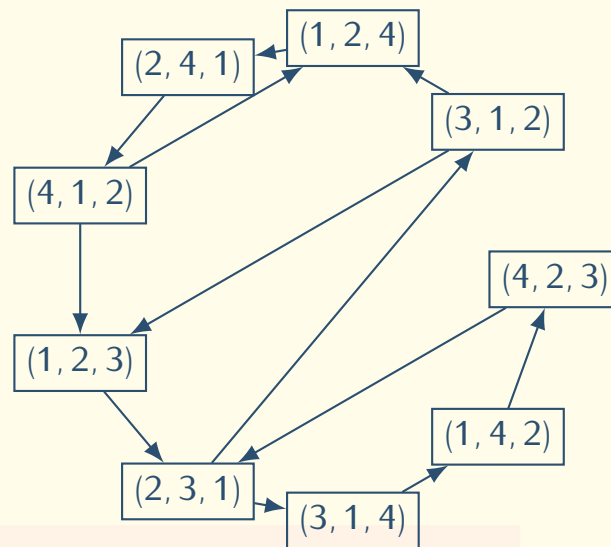
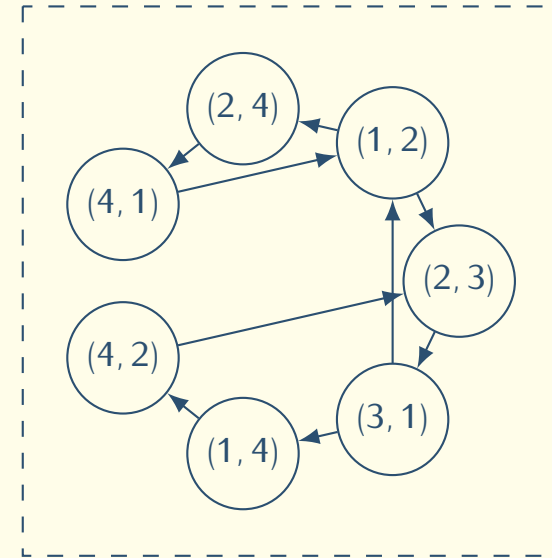
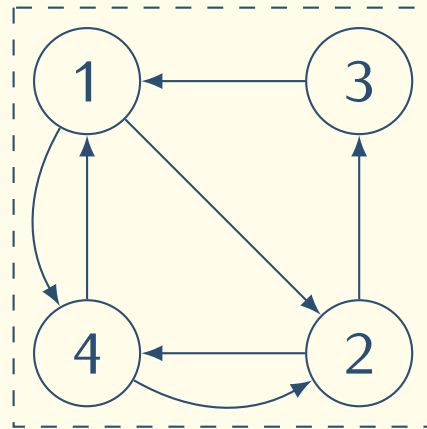
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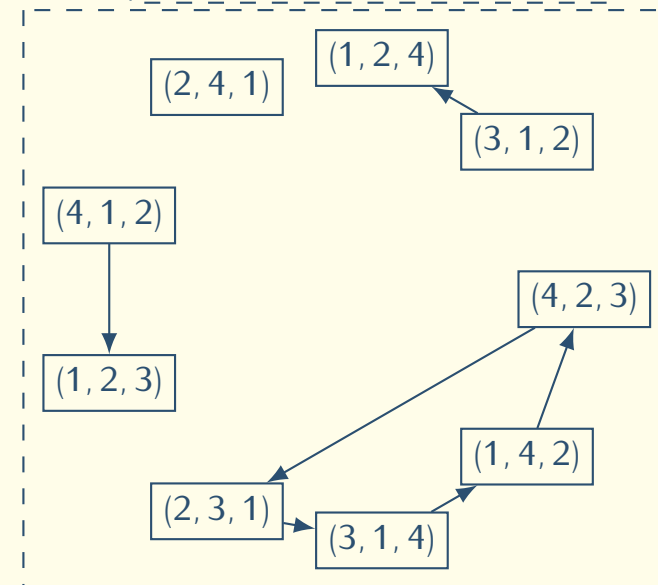
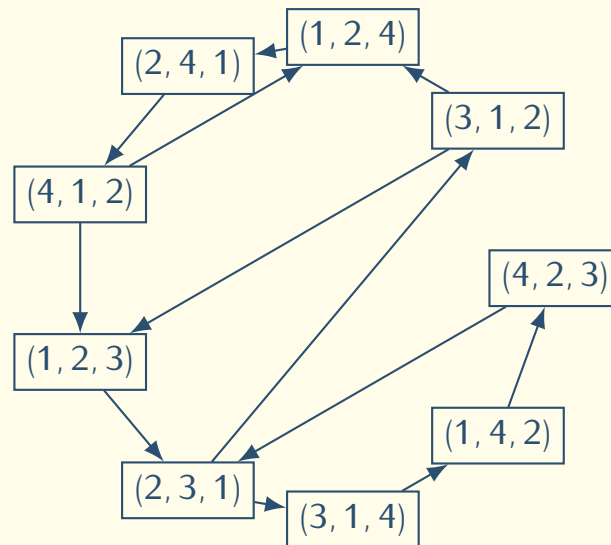
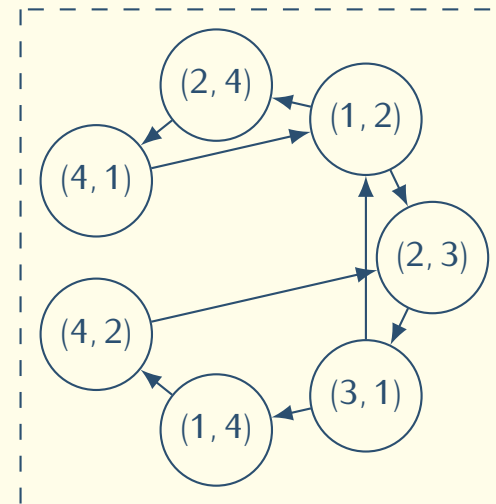
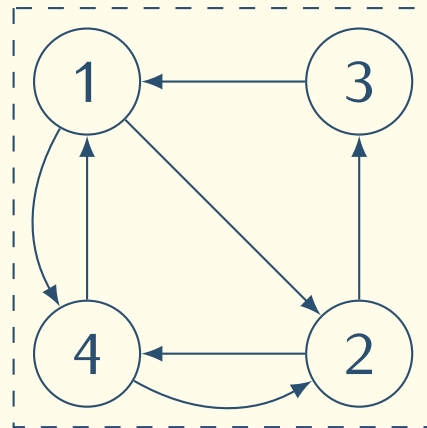
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Remark: The behaviour of the $\mathbf{x}_k(t)$ is very different from that of $\mathbf{y}_k(t)$: $\mathbf{x}_k(t)$ lacks “memory”.

- Generalize PageRank to the NBT framework.
- Downweight backtracking rather than completely eliminating it.
- Described the limiting behavior of

$$\mathbf{x}_k(t)_i = \left(\sum_{r=0}^{\infty} c_r t^r p_{r;k}(A) \right)_{ii} \quad \text{and} \quad \mathbf{y}_k(t)_i = \left(\sum_{r=0}^{\infty} c_r t^r p_{r;k}(A) \mathbf{1} \right)_i$$

as $t \rightarrow 0$ and $t \rightarrow \bar{t}_k$, for $A^T = A$ and for all $k \geq 2$.

- *Ongoing work*: general limiting results, temporal networks and ad hoc numerical techniques.

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